

* Important Announcement about Final Exam *

- Final will be a "take-home test" available on May 6, at 2:30 PM on BLACKBOARD
- Submission deadline (by email): May 13, at 2:30 PM.

Remaining Lectures: Apr 1, Apr 8, Apr 15, Apr 22, Apr 29

Last week: $(M^m, \overset{\langle \cdot, \cdot \rangle}{g})$ Riemannian manifold

$\leadsto \exists!$ Levi-Civita connection D on TM s.t. $\begin{cases} Dg \equiv 0 \\ T \equiv 0 \end{cases}$

\leadsto Riem. curvature $R \in T(\wedge^2 T^*M \otimes \text{End}(TM))$.

$$R(X, Y)Z := D_X D_Y Z - D_Y D_X Z - D_{[X, Y]} Z \quad \forall X, Y, Z \in \mathcal{X}(M)$$

lower index by g

$$\Rightarrow R(X, Y, Z, W) := -\langle R(X, Y)Z, W \rangle$$

Riem. curvature as $(0, 4)$ -tensor

Symmetries of R_{ijkl}

- (#) $\left\{ \begin{array}{l} (1) R_{ijkl} = -R_{jikl} = -R_{ijlk} \\ (2) \text{ (1st Bianchi) } R_{ijkl} + R_{iklj} + R_{iljk} = 0 \\ (3) R_{ijkl} = R_{klij} \end{array} \right.$

(#) $\Rightarrow \mathcal{R}_p : \wedge^2 T_p M \times \wedge^2 T_p M \rightarrow \mathbb{R}$ curvature operator

$$R(e_i \wedge e_j, e_k \wedge e_l) := R_{ijkl} \quad \text{for } \{e_i\} \text{ ONB for } T_p M.$$

In particular, $R(e_i \wedge e_j, e_i \wedge e_j) =: K(\pi)$ where $\pi^2 = \text{span}\{e_i, e_j\} \subseteq T_p M$

1st trace \Rightarrow Ricci curvature $\overset{\text{symm } (0, 2)\text{-tensor}}{\text{Ric}}(X, Y) := \sum_{i=1}^m R(X, e_i, Y, e_i) \quad [R_{ik} = R_{ij}{}^j{}_i]$

2nd trace \Rightarrow Scalar curvature $R := \sum_{i=1}^m \text{Ric}(e_i, e_i) = \sum_{i, j=1}^m R(e_i, e_j, e_i, e_j)$

$$\text{function} \quad [R = R_i{}^i = R_{ij}{}^{ij}]$$

Algebraic decomposition

$$Riem = W + \frac{1}{m-2} Ric \circ g + \frac{R}{2m(m-1)} g \circ g$$

Recall: **General setup**: (Bianchi identity) $D\Omega \equiv 0$, $D: T(\wedge^2 T^*M \otimes \text{End}(E)) \rightarrow T(\wedge^3 T^*M \otimes \text{End}(E))$

locally, this is $d\Omega = \Omega \wedge \omega - \omega \wedge \Omega$.

Q: What about in particular for Riem. setting?

Let $p \in M$, and fix a "normal" coord. x^1, \dots, x^m centered at p

i.e. $x^i(p) = 0$ and " $\Gamma_{ij}^k(0) = 0$ " $\Rightarrow \omega(p) = 0$

Write locally: $\Omega_j^i = \frac{1}{2} \sum_{k,l} R_{jkl}^i dx^k \wedge dx^l$

$$0 \stackrel{\text{at } p}{=} \underset{\text{Bianchi}}{d\Omega_j^i} = \frac{1}{2} \sum_{k,l,n} \underbrace{R_{jkl,n}^i}_{\frac{\partial}{\partial x^n}(R_{jkl}^i)} dx^n \wedge dx^k \wedge dx^l \quad \text{at } p$$

$\frac{\partial}{\partial x^n}(R_{jkl}^i) = (D_{\partial_n} R)(\partial_i, \partial_j, \partial_k, \partial_l) =: R_{jkl;n}^i$

At p: $R_{jkl;n}^i + R_{jln;k}^i + R_{jnk;l}^i = 0$

OR lower its index: (*) $R_{ijkl;n} + R_{ijln;k} + R_{ijnk;l} = 0$ 2nd Bianchi identity

i.e. $\underbrace{(DR)(x, y, z, u, v)}_{ii} + (DR)(x, y, u, v, z) + (DR)(x, y, v, z, u) \equiv 0$
 $(D_{\nu} R)(x, y, z, u)$

Defⁿ: (Divergence) Let e_1, \dots, e_m be an O.N.B. of $T_p M$.

$\bullet X \in \mathfrak{X}(M) \Rightarrow \text{div } X(p) := \sum_{i=1}^m \langle D_{e_i} X, e_i \rangle(p)$ $\text{div } X \in C^0(M)$

$\bullet h \in T(T_2^0 M) \Rightarrow \text{div } h(p) := \sum_{i=1}^m (D_{e_i} h)(e_i, \cdot)(p)$ $\text{div } h \in \Omega^1(M)$

Symmetric (0,2)-tensor

Locally $\text{div } X = X^i{}_{;i}$ & $(\text{div } h)_j = h^i{}_{;j} = \overset{\text{O.N.B.}}{=} h_{ij}{}^{;i}$

Contract i, k in (*) \Rightarrow (*) $R_{jens;i} + R_{ijens;i} - R_{jnsl} = 0$ contracted 2nd Bianchi

Contract

$$j.l \Rightarrow R_{;n} - R_{in;i} - R_{in;i} = 0$$

in (**)

$$\Rightarrow 2 R_{in;i} = R_{;n}$$

i.e. (***) $2 \operatorname{div} \operatorname{Ric} = dR$

twice-contracted
2nd Bianchi

Sometimes, we write:

$$\operatorname{div} G = 0$$

where G is the Einstein tensor

$$G_{ij} := R_{ij} - \frac{R}{2} g_{ij} \quad \text{(0,2)-tensor symm.}$$

(Note: $\overset{\circ}{\operatorname{Ric}}_{ij} := R_{ij} - \frac{R}{m} g_{ij}$)

Application of 2nd Bianchi:

"constant Ricci"

Defⁿ: (M^m, g) is Einstein if $\operatorname{Ric}(g) = \frac{R_0}{m} g$ for some constant $R_0 \in \mathbb{R}$ (E)

Remark: It's an important question for which M^m possess Einstein metric g ?

Note: (E) take trace $\Rightarrow R(g) \equiv \frac{R_0}{m} \cdot m \equiv R_0$

So, (M, g) Einstein $\Rightarrow \overset{\circ}{\operatorname{Ric}} \equiv 0$ & $R \equiv \text{const. } (= R_0)$.

(NOT true when $m=2$)

Schur's Thm: $\overset{\circ}{\operatorname{Ric}} \equiv 0 \Rightarrow (M, g)$ Einstein for $m \geq 3$

Pf: $\overset{\circ}{\operatorname{Ric}} \equiv 0 \Rightarrow \operatorname{Ric}_p \stackrel{(+)}{\equiv} \frac{R_p}{m} g_p$ here: $R = \operatorname{tr}(\operatorname{Ric}) \in C^\infty(M)$ may not be const.

Claim: $R \equiv \text{const.}$ when $m \geq 3$.

(***) $\Rightarrow \frac{1}{2} dR = \operatorname{div} \operatorname{Ric} \stackrel{(+)}{=} \frac{1}{m} dR$

$m \neq 2 \Rightarrow dR \equiv 0 \Rightarrow R \equiv \text{const.}$

Cor: Let $m \geq 3$. Suppose the sectional curvatures are "isotropic", i.e. $\exists f \in C^\infty(M)$

st. $K_p(\pi) = f(p) \quad \forall \pi^2 \in T_p M$

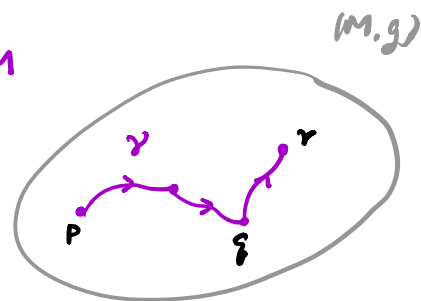
Then, $f \equiv \text{const.}$ (i.e. (M, g) has const. sectional curvature.)

Metric Geometry on (M^m, g) - connected.

Defⁿ: The **length** of a piecewise C^1 curve $\gamma: [0, 1] \rightarrow M$

is
$$L(\gamma) := \int_0^1 \|\gamma'(t)\|_g dt \geq 0$$

where $\|v\|_g := g(v, v)^{1/2}$



We can then define the **Riemannian distance function**

$$f: M \times M \longrightarrow \mathbb{R}_{\geq 0}$$

$$f(p, q) := \inf \left\{ L(\gamma) \mid \gamma: [0, 1] \rightarrow M \text{ piecewise } C^1 \right. \\ \left. \text{st. } \gamma(0) = p, \gamma(1) = q \right\} \geq 0$$

Fundamental Fact: (M, f) is a metric space whose "metric topology" agrees with the "manifold topology" on M .

Reasons: (M, f) metric space \Leftrightarrow $\begin{cases} f(p, q) = f(q, p) \checkmark \\ f(p, q) \geq 0 \text{ with " = " only } p = q \\ f(p, r) \leq f(p, q) + f(q, r) \checkmark \end{cases}$

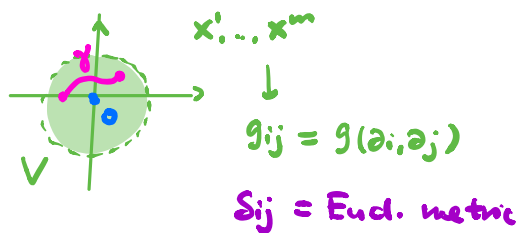
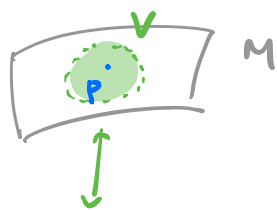
For the "non-trivial" part. Idea: Locally, g metric \approx Eucl. metric

Let $p \in M$, local coord. x^1, \dots, x^m centered at p in a nbd. V of p .

$$\exists \text{ const. } c_1, c_2 > 0 \text{ st. } c_1 \delta_{ij} \leq (g_{ij}(x)) \leq c_2 \delta_{ij} \text{ in } V$$

If $\gamma \subseteq V$, then $c_1 L_\delta(\gamma) \leq L_g(\gamma) \leq c_2 L_\delta(\gamma)$

$$\Rightarrow \underbrace{B_\delta(0, c_1 \epsilon)}_{\text{mfd topo}} \subseteq \underbrace{B_g(0, \epsilon)}_{\text{metric topology}} \subseteq \underbrace{B_\delta(0, c_2 \epsilon)}_{\text{manifold topo}} \quad \forall \epsilon > 0 \text{ small.}$$



Remark: If (M, g) is "nice", then $f(p, q)$ is realized by some γ .

Idea: These "straight lines" γ are geodesics on (M, g) .

Recall: $\gamma: [0, 1] \rightarrow (M, g)$ geodesic iff $D_{\gamma'} \gamma' \equiv 0$.

i.e.
$$\frac{d^2 x^h}{dt^2} + \Gamma_{ij}^h(x(t)) \frac{dx^i}{dt} \frac{dx^j}{dt} = 0 \quad \text{in local coord}$$

$$\gamma(t) = (x^1(t), \dots, x^n(t))$$

Note: $Dg \equiv 0 \Rightarrow \|\gamma'(t)\|_g \equiv \text{const.} = 1$ arc-length parametrization

Fact: Any C^1 regular ($\gamma' \neq 0$) curve can be reparametrized by arc-length.

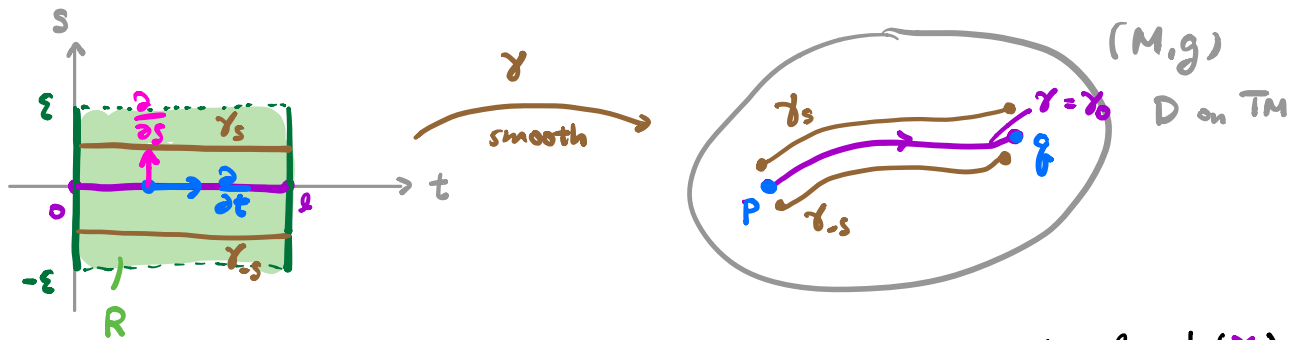
So: "geodesics" = "straight lines" on (M, g) + const. speed parametrization

Prop: Up to reparametrization, a curve $\gamma: [0, l] \rightarrow (M, g)$ is a geodesic iff γ is a "critical point" to the length functional L (with end pt fixed)

i.e. If $\gamma_s: [0, l] \rightarrow (M, g)$, $s \in (-\epsilon, \epsilon)$, is ANY 1-parameter family of (smooth) curves with $\gamma_0 = \gamma$, then

$$\left. \frac{d}{ds} \right|_{s=0} L(\gamma_s) = 0$$

Picture:



Proof: WLOG: Assume $\gamma = \gamma_0(t): [0, l] \rightarrow (M, g)$ is p.b.a.l., i.e. $l = L(\gamma_0)$.

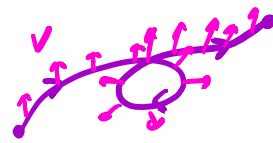
Consider the 1-parameter family as

$$\gamma(t, s) := \gamma_s(t) : \underbrace{[0, l] \times (-\epsilon, \epsilon)}_R \longrightarrow M$$

Note: (t, s) is a coord. system on R

• γ induces a pullback bundle on \mathbb{R}

$$\begin{array}{ccc} g, D & \gamma^* TM & \rightarrow TM, g, D \\ \text{pullback} & \downarrow & \downarrow \\ \text{metric} & & \\ \& \text{connection} & \mathbb{R} \xrightarrow{\gamma} M \end{array}$$



FACT: D is also a torsion-free, metric compatible connection on $\gamma^* TM$.

Then, $L(\gamma_s) := \int_0^l \|\gamma'_s(t)\|_g dt := \int_0^l \|\gamma_* \left(\frac{\partial}{\partial t} \right)\|_g dt$.
velocity field

Denote: $V := \gamma_* \left(\frac{\partial}{\partial s} \Big|_{s=s_0} \right) \in T(\gamma_0^* TM)$ variation field along γ_0

We compute:

$$\frac{d}{ds} \Big|_{s=s_0} L(\gamma_s) = \int_0^l \frac{\langle D_{\frac{\partial}{\partial s}} \gamma_* \left(\frac{\partial}{\partial t} \right), \gamma_* \left(\frac{\partial}{\partial t} \right) \rangle}{\|\gamma_* \left(\frac{\partial}{\partial t} \right)\|} \Big|_{s=s_0} dt$$

$\because \gamma_0$ p.b.a.l. $\implies 1$

$\because D$ is torsion-free \implies
 $\because \left[\frac{\partial}{\partial t}, \frac{\partial}{\partial s} \right] \equiv 0$

$$= \int_0^l \langle D_{\frac{\partial}{\partial s}} \gamma_* \left(\frac{\partial}{\partial t} \right), \gamma_* \left(\frac{\partial}{\partial t} \right) \rangle \Big|_{s=s_0} dt$$

$$= \int_0^l \langle D_{\frac{\partial}{\partial t}} V^{(t)}, \gamma'_0(t) \rangle dt$$

$\because D$ is metric compatible

$$= \int_0^l \frac{\partial}{\partial t} \left(\langle V^{(t)}, \gamma'_0(t) \rangle \right) - \langle V^{(t)}, D_{\frac{\partial}{\partial t}} \gamma'_0(t) \rangle dt$$

$$= \langle V(t), \gamma'_0(t) \rangle \Big|_{t=0}^{t=l} - \int_0^l \langle V, D_{\frac{\partial}{\partial t}} \gamma'_0 \rangle (t) dt$$

$$\frac{d}{ds} \Big|_{s=s_0} L(\gamma_s) = \langle V(t), \gamma'_0(t) \rangle \Big|_{t=0}^{t=l} - \int_0^l \langle V, D_{\frac{\partial}{\partial t}} \gamma'_0 \rangle (t) dt$$

1st variation formula for length functional

If endpoints are fixed, then $V(0) = 0 = V(l)$ and

$$\frac{d}{ds} \Big|_{s=s_0} L(\gamma_s) = 0 \iff - \int_0^l \langle V, D_{\frac{\partial}{\partial t}} \gamma'_0 \rangle dt = 0 \iff D_{\gamma'_0} \gamma'_0 \equiv 0$$

\forall variation $\{\gamma_s\}$ of γ_0 $\forall V \in T(\gamma_0^* TM)$ geodesic!

Exponential Map & Geodesic Normal Coordinates

Recall: Fix $p \in M$, $v \in T_p M$, then

(IVP):
$$\begin{cases} D_{\gamma} \gamma' \equiv 0 \text{ along } \gamma & \text{has unique sol}^2 \text{ on some short interval:} \\ \gamma(0) = p & \gamma_{p,v} := \gamma : (-\epsilon, \epsilon) \rightarrow M \\ \gamma'(0) = v \end{cases}$$

Note: ϵ depends on p, v .

BUT, $\gamma_{p,v}$ and ϵ depends smoothly on p, v .

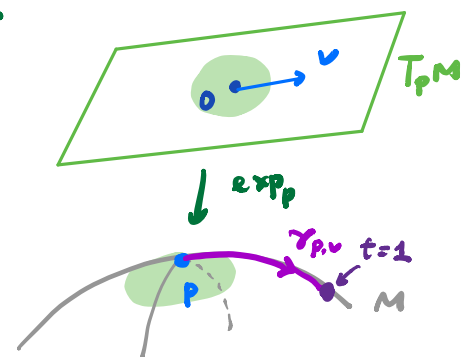
Homogeneity of geodesics: $\gamma_{p, \lambda v}(t) = \gamma_{p,v}(\lambda t) \quad \forall \lambda \in \mathbb{R}$



$$\begin{aligned} \gamma_{p,v} &: (-\epsilon, \epsilon) \rightarrow M \\ \Rightarrow \gamma_{p, \lambda v} &: \left(-\frac{\epsilon}{\lambda}, \frac{\epsilon}{\lambda}\right) \rightarrow M \end{aligned}$$

By cptness, the exponential map of (M, g) at $p \in M$:

$$\begin{array}{ccc} \text{exp}_p : \mathcal{U} \subseteq T_p M & \xrightarrow{\circ} & M \\ \downarrow v & & \downarrow \gamma_{p,v}(1) \end{array}$$



is well-defined in some nbd. $\mathcal{U} \subseteq T_p M$
(and smooth)

Prop: $d(\text{exp}_p)|_0 : T_p M \rightarrow T_p M$ is the identity map.

$$\begin{aligned} \text{Pf: } d(\text{exp}_p)_0(v) &:= \frac{d}{ds} \Big|_{s=0} \text{exp}_p(sv) := \frac{d}{ds} \Big|_{s=0} \gamma_{p,sv}(1) \\ &= \frac{d}{ds} \Big|_{s=0} \gamma_{p,v}(s) = \gamma'_{p,v}(0) = v \end{aligned}$$

By I.F.T., exp_p is a local diffeo at 0.

$$\text{exp}_p : \mathcal{U} \xrightarrow[\cong]{\text{diffe.}} \mathcal{V}$$

defines the geodesic normal coordinates near p .

